



From Pilot to Production: Practical Considerations in Your RFID Deployment

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Who We Are

- ◆ Evaluate RFID products in a *scientific* way
- ◆ Provide useful, timely, credible, and unbiased data to end users of RFID products
- ◆ Constituents
 - ◆ **University of Kansas / ITTC:** Primary research contributor
 - ◆ **RFID Journal:** Initial funding, distributor, advertisement
 - ◆ **Rush Tracking Systems:** Initiator, industry lesion
- ◆ Business model
 - ◆ Sell reports (~\$1,000 / report) to finance future reports
 - ◆ Look for release in April
 - ◆ Sponsorships
 - ◆ Research projects
- ◆ ITTC/KU Applied Research Labs solve hard problems
 - ◆ Direction of travel through portal w/ Seknion
 - ◆ Tagging metal assets
 - ◆ Passive sensor tags
- ◆ Intellectual property
 - ◆ 4 patents pending
 - ◆ 2 Licenses signed
 - ◆ Product available in 2Q07
 - ◆ More in the pipe
- ◆ Basic research
 - ◆ RFID privacy using CDMA



Big Picture

◆ What factors affect whether RFID will work for you:

◆ Cost

- ◆ Tags and readers small part

◆ Performance

- ◆ How far, how fast

◆ Reliability

- ◆ Nothing in life is 100%

◆ Robustness

- ◆ Will it survive

◆ Environment

- ◆ Noise, obstacles, other readers, RF equipment

◆ Longevity

- ◆ Battery life
- ◆ Wear-and-tear

◆ Integration

- ◆ Will it work with your information systems

◆ ROI

- ◆ How much, how soon

◆ Support

- ◆ Can I support the technology in 5-10 years?



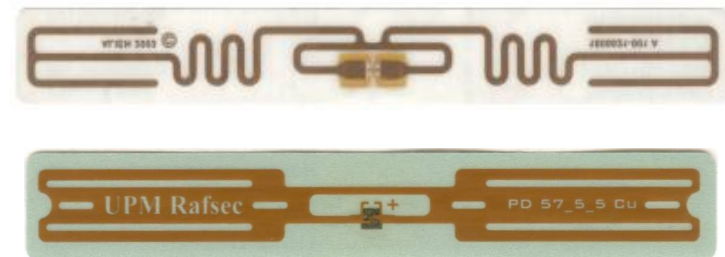
- ◆ Present *technical* aspects to making tags, readers work

- ◆ Take home:
 - ◆ How the different technologies work
 - ◆ What impact the environment has
 - ◆ When to use different technologies
 - ◆ What to expect from RFID systems
 - ◆ Where the future is headed



Outline

- ◆ A brief lesson in physics (electromagnetics)
- ◆ An overview of the technologies
 - ◆ According to frequency
 - ◆ According to capability
- ◆ Focus on UHF
 - ◆ Tags
 - ◆ Readers
 - ◆ Looking forward





A Brief Lesson in Physics (Electromagnetics)



◆ Coupling via three modes:

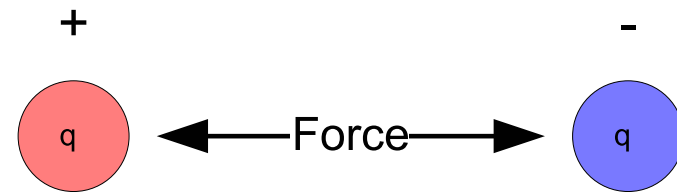
- ◆ Electrostatics
- ◆ Magnetics
- ◆ Electromagnetics



Electrostatics

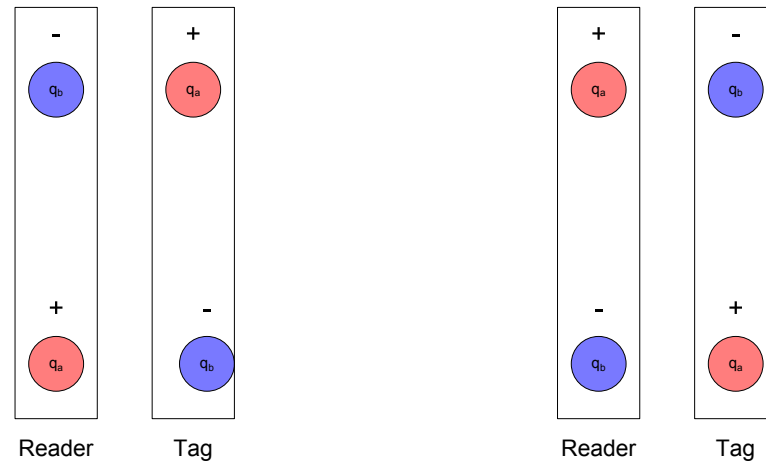
Opposites attract
(and likes repel)

$$F = k_c \frac{|q_a||q_b|}{d^2}$$





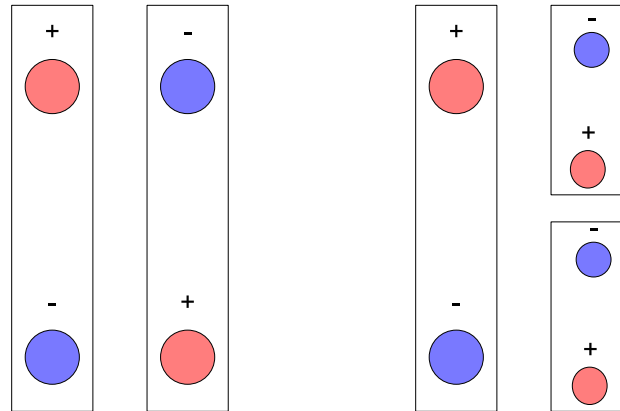
Power Transfer



- ◆ By changing distribution of charges on reader antenna, you can force charges to move in the tag
- ◆ Communicate by modulating the flow of charges over time



Backscatter Communication

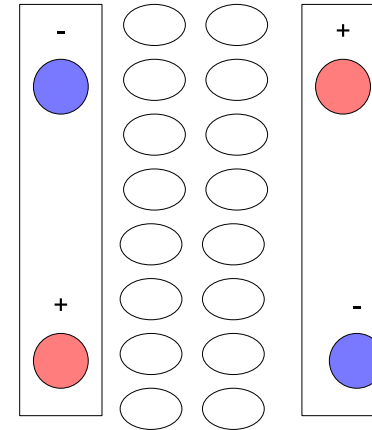


- ◆ By interrupting the flow of charges, tag can communicate back to the reader
 - ◆ Reader senses that it is harder to separate charges on its antenna

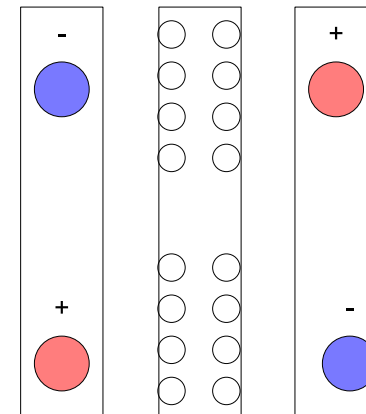


Properties of Electrostatic Coupling

Dielectric material
enhances performance



Intervening metal has
little affect





Summary

- ◆ Electrostatic coupling:
 - ◆ Works over very short distances (mm)
 - ◆ Enhanced by dielectrics
 - ◆ Little affect by intervening metals
 - ◆ Requires low frequencies for operation (HF)

- ◆ Products:
 - ◆ Virtually none



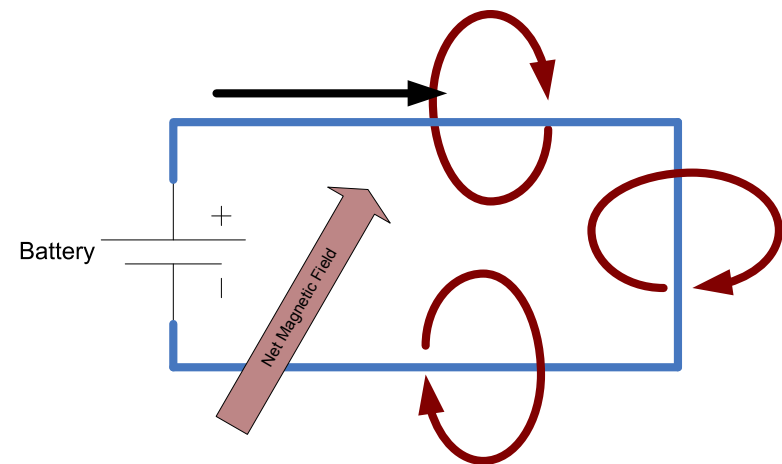
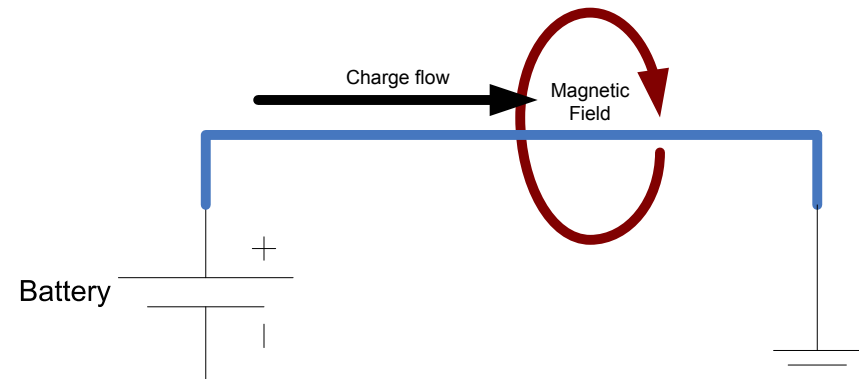
Magnetics

- ◆ Moving charges create a magnetic field

$$\mathbf{B} = \mathbf{v} \times \frac{\mathbf{E}}{c^2}$$

$$\mathbf{F} = q\mathbf{v} \times \mathbf{B}$$

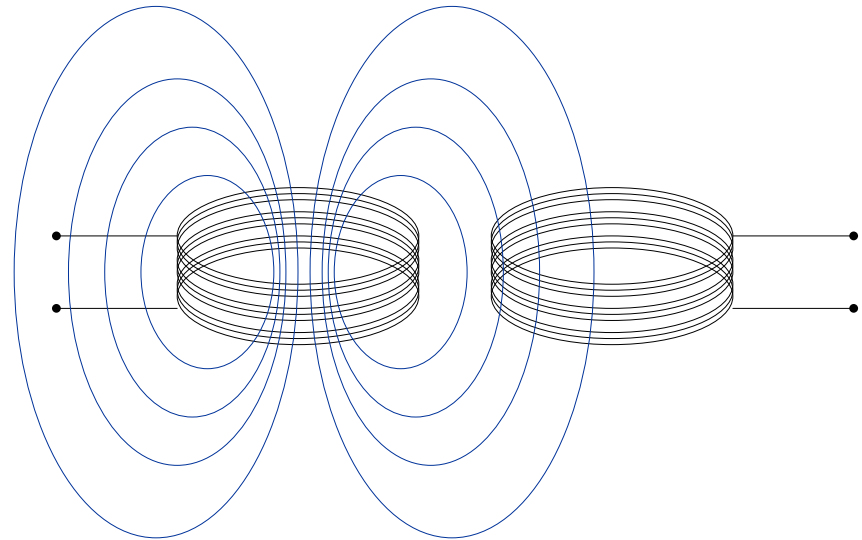
- ◆ Loops “focus” magnetic fields like a lens





Power Transfer

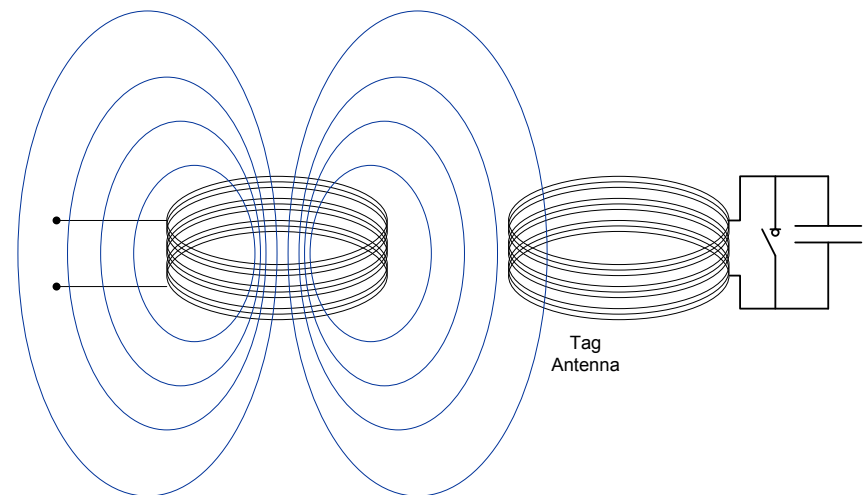
- ◆ Two loops can be coupled when
 - ◆ H lines of one loop flow through another loop
 - ◆ Described by k , can be as low as 0.01
- ◆ Just as I (current) induces H , H induces I
 - ◆ How power transfers from reader to tag





Communication

- ◆ Tag to reader
 - ◆ Tag current creates H , induces I on reader antenna
 - ◆ By varying tag I , can vary I in reader
 - ◆ (Capacitor used to “tune” the antenna for optimal efficiency)





Properties of Magnetic Coupling

- ◆ Magnetic fields *not affected* by dielectrics (e.g., water)
- ◆ Magnetic fields *blocked* by metals
 - ◆ Limited penetration at lower frequencies
- ◆ Dielectrics near tags can still cause problems
 - ◆ Changes resonant frequency of antenna
 - ◆ Dielectric loss can reduce efficiency
- ◆ Metals near tags cause problems
 - ◆ Change resonant frequency of antenna
 - ◆ Reduces efficiency

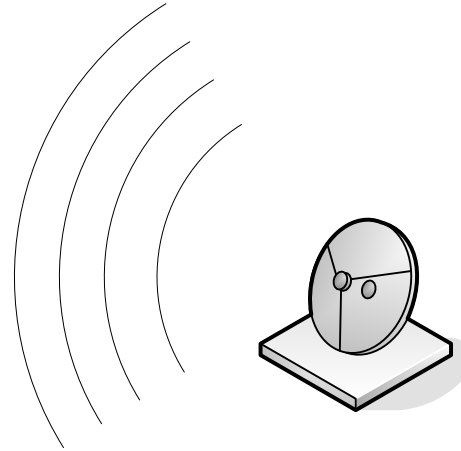


Summary of Magnetic Coupling

- ◆ Commonly use loop antennas
- ◆ Magnetic *fields* not affected by dielectrics (e.g., water)
- ◆ Antennas *are* affected by dielectrics
- ◆ Magnetic fields blocked by metal
- ◆ Metal near tag antennas cause problems
- ◆ Frequencies: low through very high
 - ◆ Reduced read distance with higher frequencies
- ◆ Read distance: mm to m



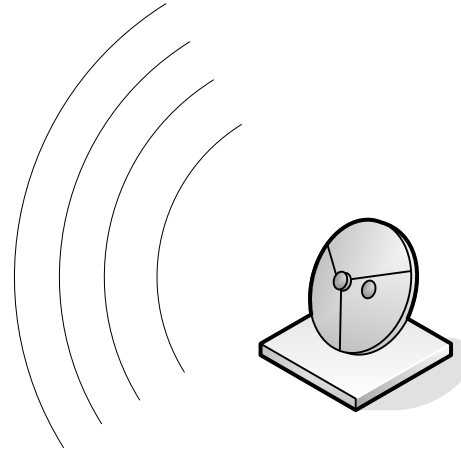
Electromagnetics



- ◆ Think: *radar, light*
- ◆ Typically for high frequencies (short wavelengths) and/or long distances



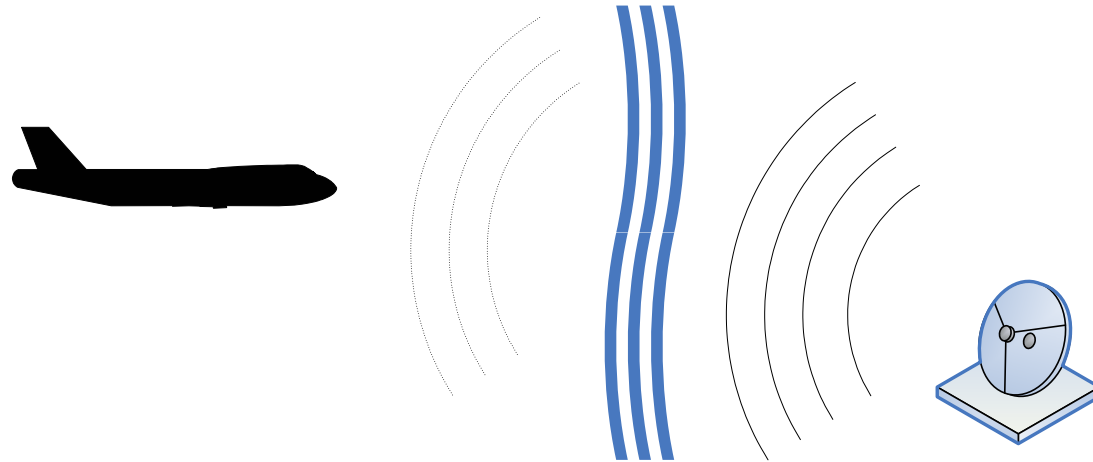
Power Transfer



- ◆ Waves carry the power
 - ◆ Solar cells turn light to electricity
 - ◆ Microwave ovens turn 2.4 GHz RF into dinner
 - ◆ Induces currents on a wire, similar to electrostatics



Affects of Material

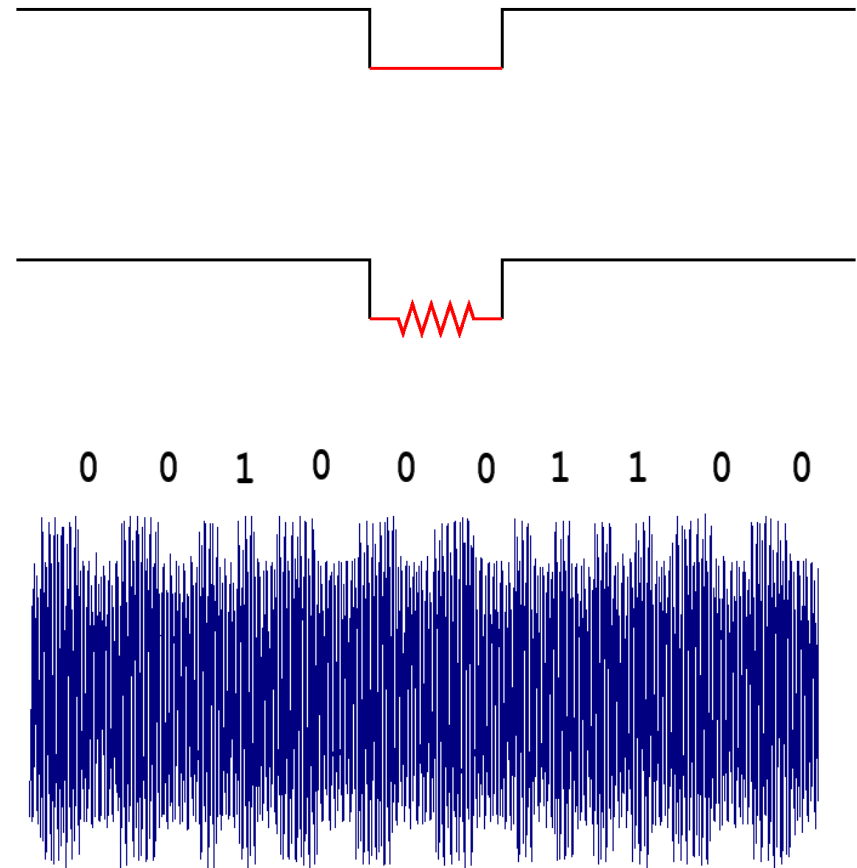


- ◆ Materials readily interfere
 - ◆ Metal reflects, water absorbs
 - ◆ Some materials reflect some and absorb some (e.g., tinted glass)
 - ◆ Some are mostly transparent (foams, simple plastics)



Backscatter Communication

- ◆ Tag modulates RCS
- ◆ Short (or open):
 - ◆ large RCS
- ◆ Matched load:
 - ◆ power → heat
 - ◆ smaller RCS
- ◆ Binary modulate RCS over time
 - ◆ ASK, FSK, etc.





Active Tags

- ◆ Only enough power transfer to communicate



- ◆ No backscatter
 - ◆ Transmit / response





Comparison of Capabilities

	Passive	BAT	Active
RF output	30 dBm	30 dBm	20 dBm
Modulation correction	0 dB	-3 dB	0 dB
Reader Gain	6 dBi	6 dBi	0 dBi
Path loss: 3 meters	-41 dB	-41 dB	-41 dB
Receiver antenna gain	2 dBi	2 dBi	0 dBi
Received power	-3 dBm	-6 dBm	-21 dBi
Necessary power	-11 dBm	-42 dBm	-70 dBm
Margin	8 dB	36 dBm	49 dBm
Estimated range	7.6 m	192 m	862 m



Summary of Electromagnetic Coupling

- ◆ Long distance communication
- ◆ Sensitive to intervening materials
 - ◆ X-ray reads generally require BAT, active tagging
- ◆ Materials tend to de-tune antennas
- ◆ Frequencies: 300 MHz +



Summary of Technologies



Frequency

- ◆ Low Frequency (LF)
 - ◆ 125—135 KHz (long wavelength)
 - ◆ Near-field only (usually inductive)
 - ◆ Passive used for animal, near-contact industrial
 - ◆ Active LF tags being developed (IEEE 1902.1 “Rubee”)
- ◆ High Frequency (HF)
 - ◆ Typically 13.56 MHz
 - ◆ Inductive near-field passive only
 - ◆ ISO 14443, 15693
- ◆ Ultra-High Frequency + (UHF, microwave)
 - ◆ 433 MHz (active), ~900 MHz, 2.4 GHz (passive, active)
 - ◆ Usually electromagnetic coupling, some near-field UHF
 - ◆ ISO 18000-6c “Gen 2”



Functionality

- ◆ Passive (e.g., ISO 18000-6c)
 - ◆ No internal power source
 - ◆ Short distances
 - ◆ Low cost
- ◆ Battery-assisted (e.g., Intellex)
 - ◆ Battery powers circuit, not communication
 - ◆ Moderate distances
 - ◆ Moderate costs
- ◆ Active (e.g., ISO 18000-7 WIP)
 - ◆ Battery powers circuit, communications
 - ◆ Longer distances
 - ◆ Higher costs
- ◆ Sensing
 - ◆ Requires active tags
 - ◆ E.g., temperature, impact, sound, light, GPS, LPS, etc.
- ◆ Interrogating
 - ◆ “Tags” interact as peers
 - ◆ “Ad hoc networks”
 - ◆ E.g., 802.11, Bluetooth, Zigbee, etc.



Supply Chain Management

Supply chain has focused on passive, active UHF

- ◆ Dock doors demand “feet” of read distances
- ◆ Temperature-aware requires active, data logging
- ◆ Cold temperatures can create demanding environments
 - ◆ Frequently tagging liquid contents
 - ◆ Frost / moisture from environment
 - ◆ Temperature can interfere with adhesives

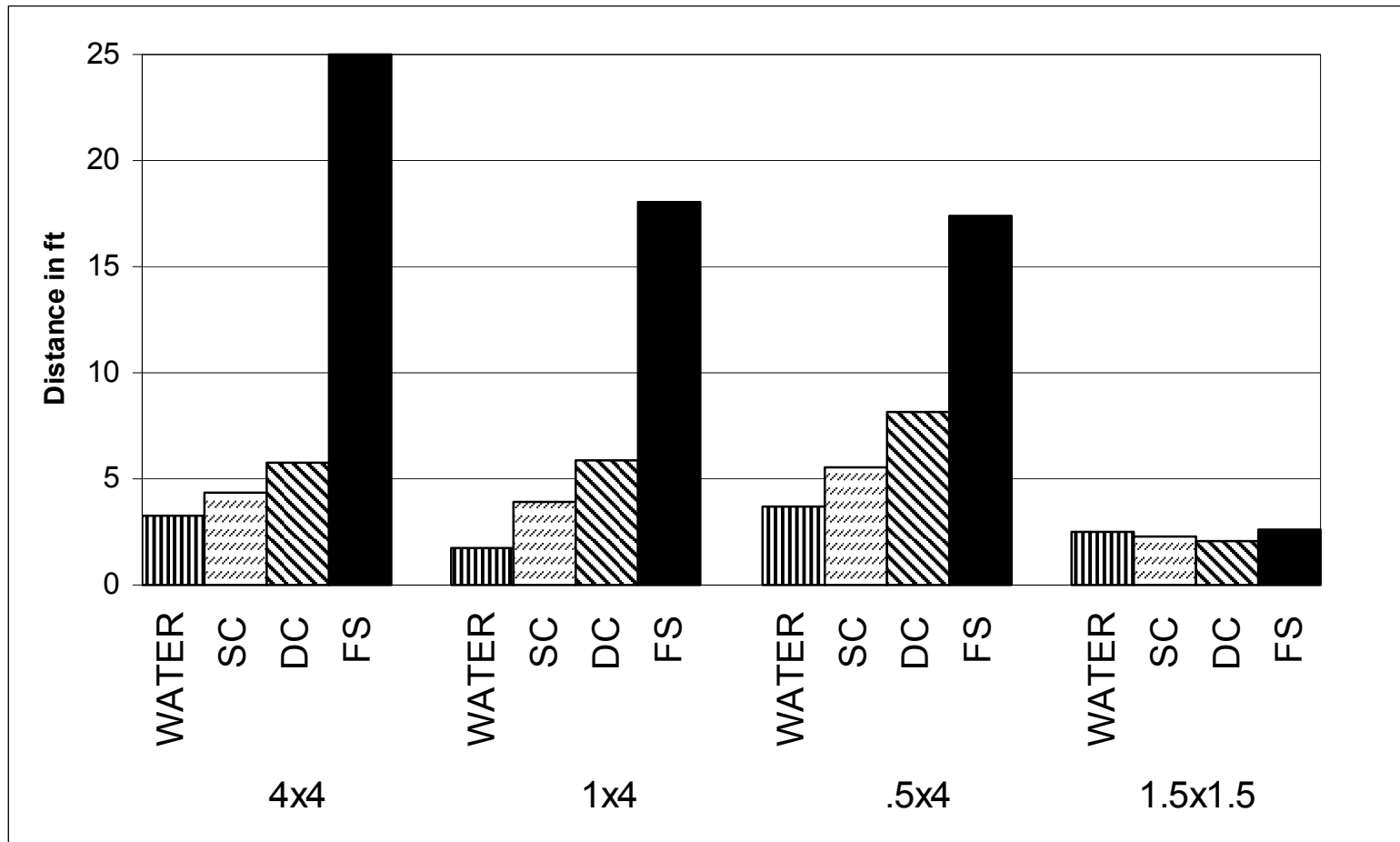


Factors with Passive UHF

- ◆ What are you tagging
 - ◆ Metal, water give problems
- ◆ What tags to choose
 - ◆ Impacts performance, cost
- ◆ How to select a reader
 - ◆ Impacts cost, bulk, complexity
- ◆ How to get the most out of your tags

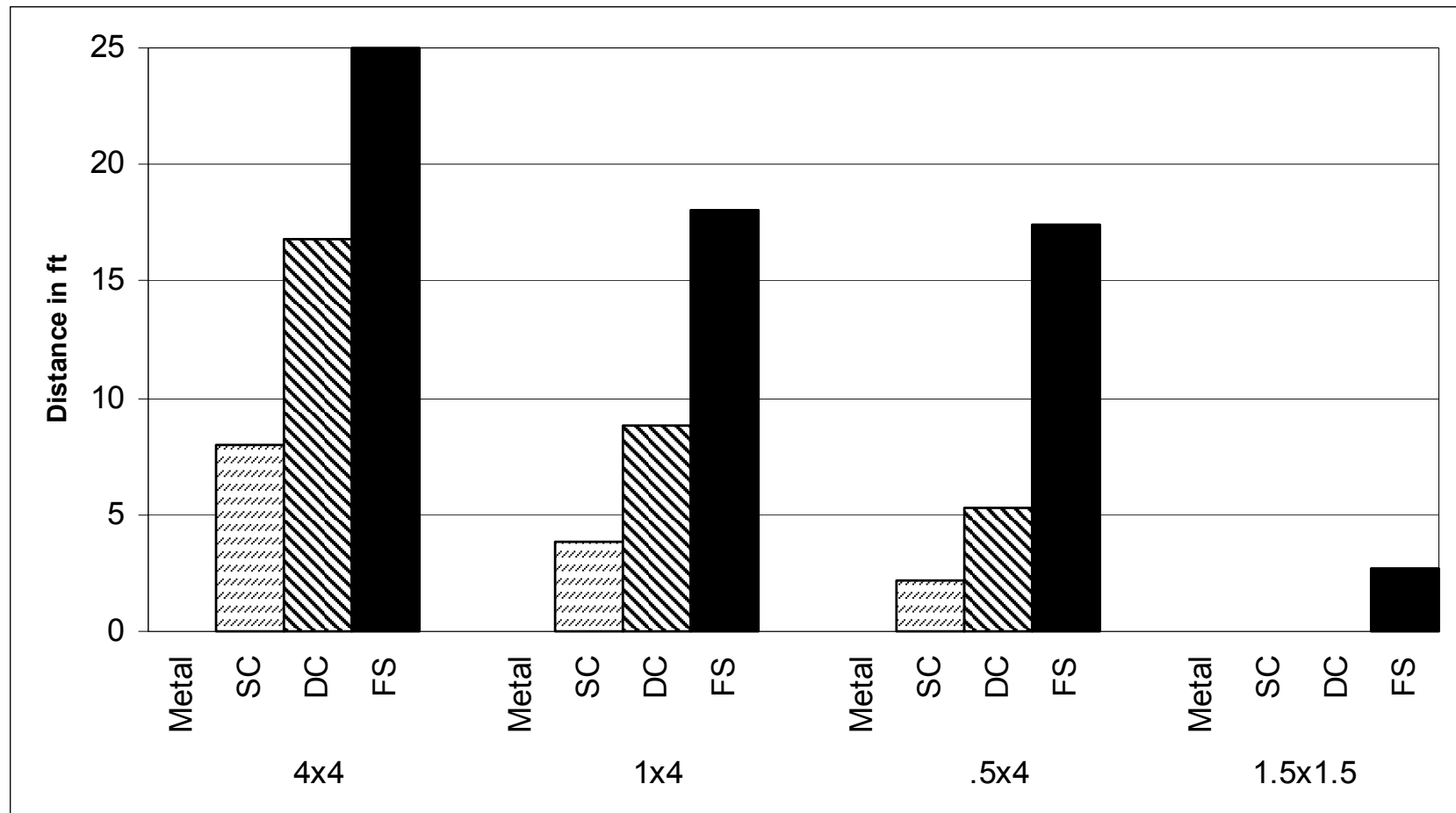


Water Degrades Performance



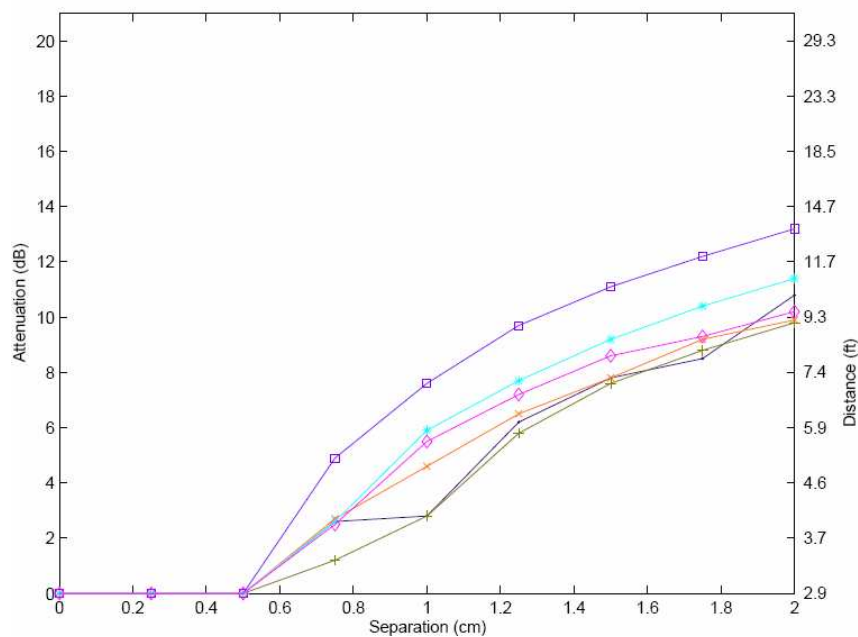


Metal Degrades Performance

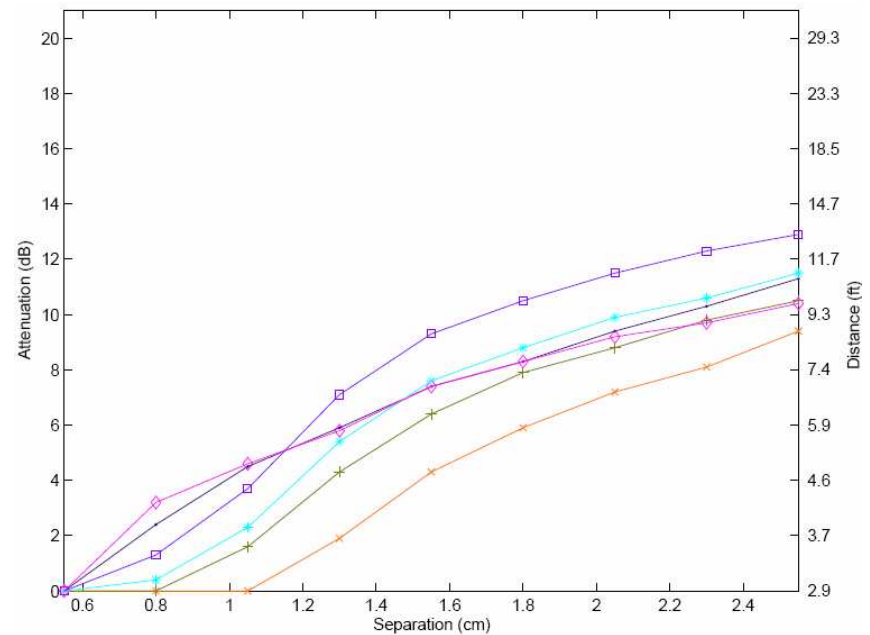




Experimental Data: Tag Performance vs. Separation



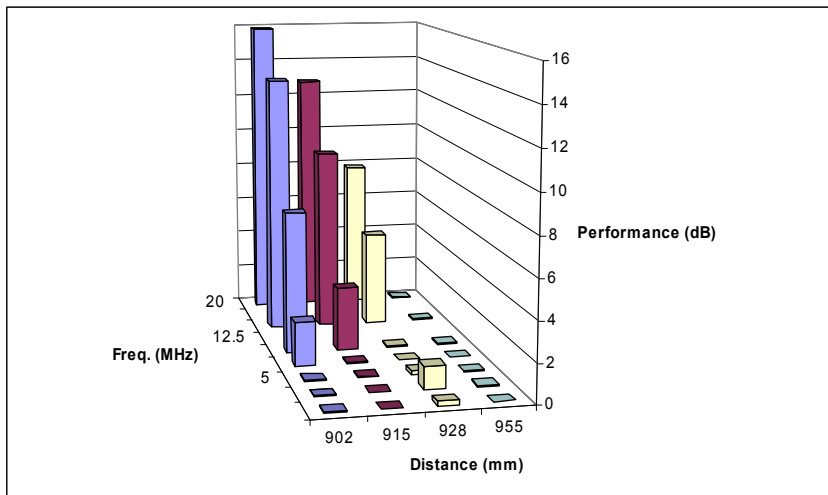
Separation from Metal



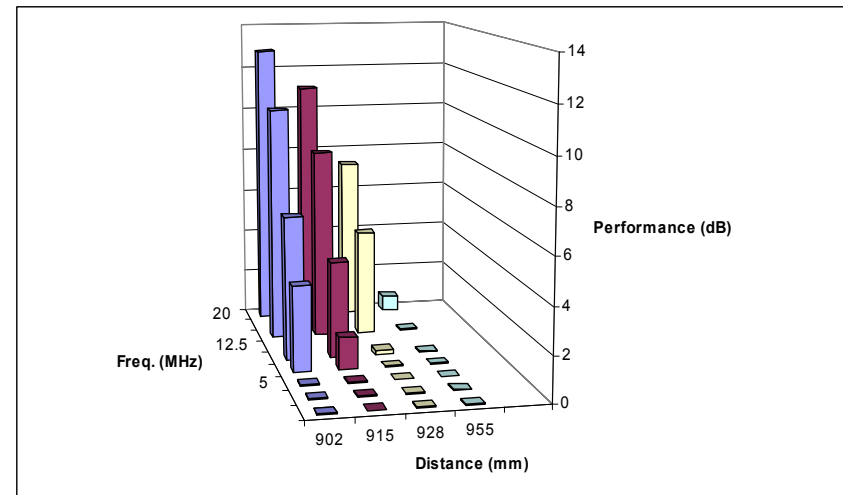
Separation from Water



Experimental Data: Tag Performance vs. Separation



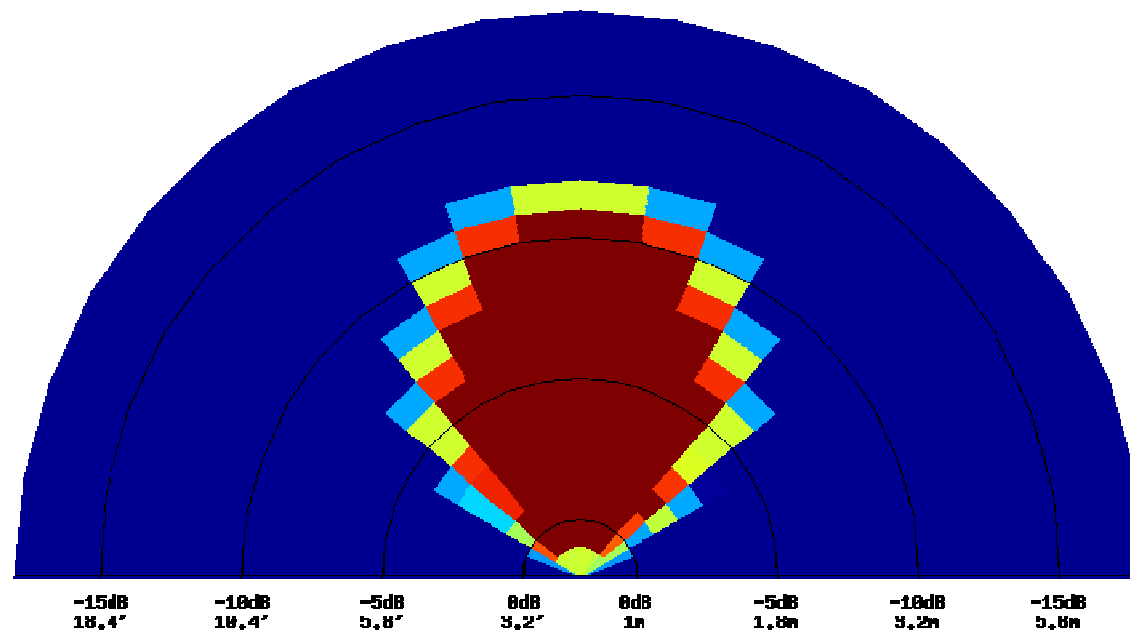
Separation from Metal



Separation from Water

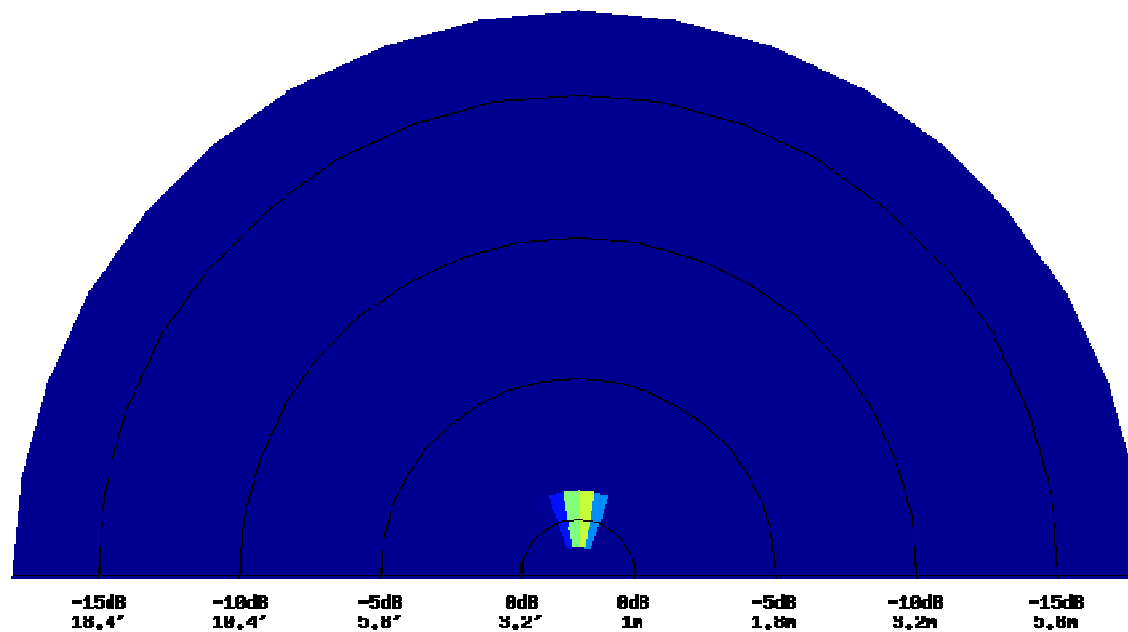


Metal Changes Orientation Sensitivity of “Omni” tag



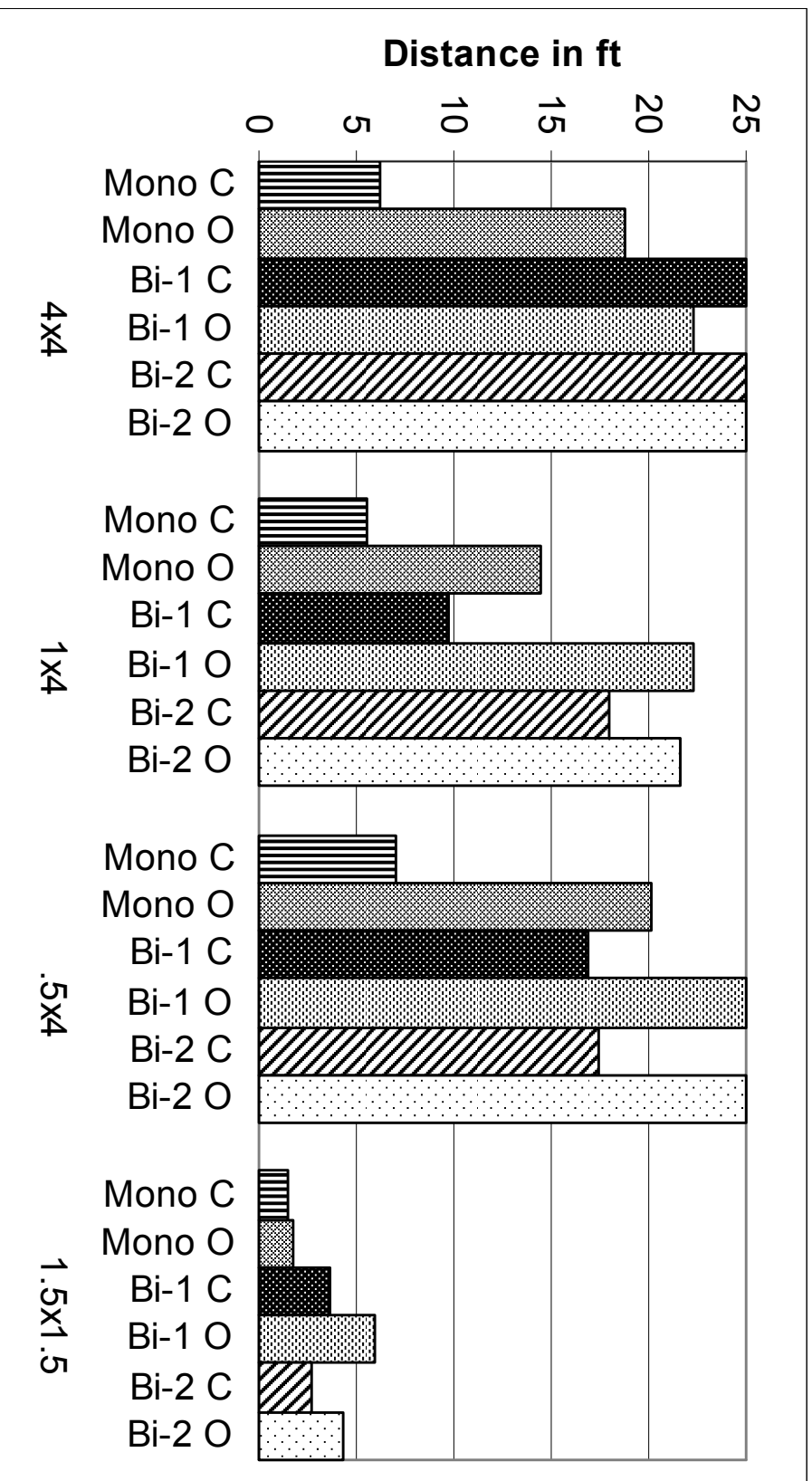


Some tags *crippled* by metal





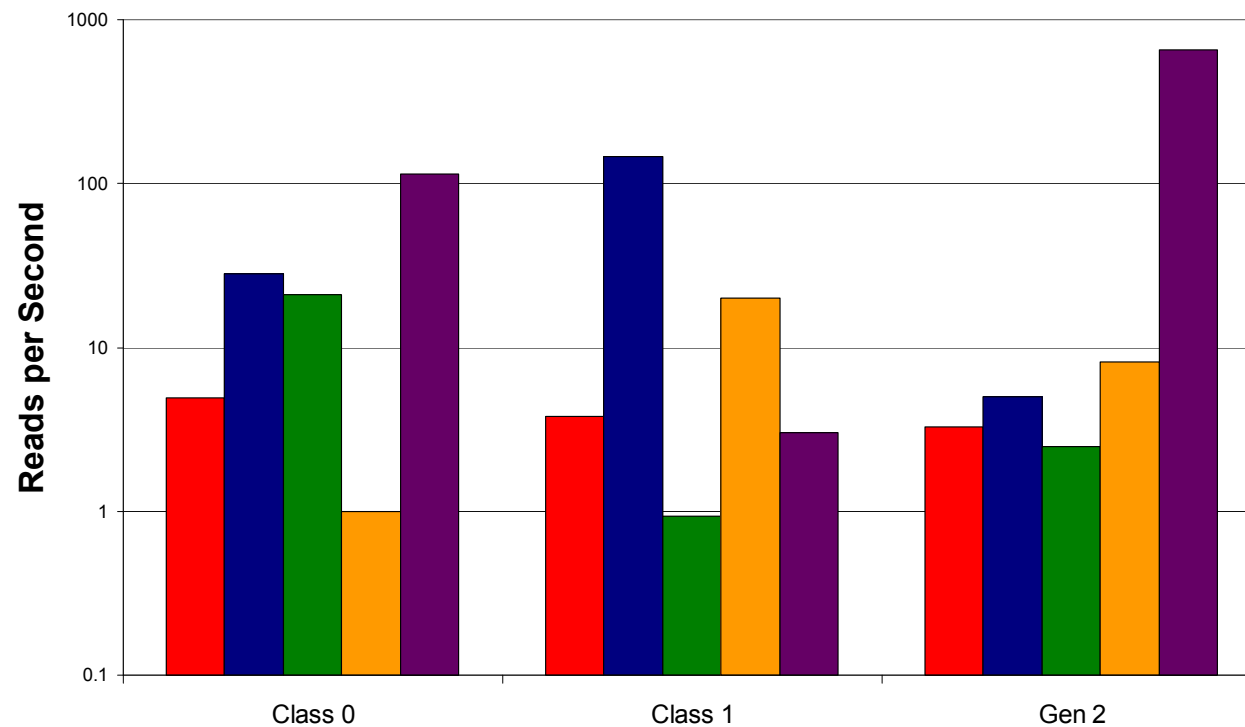
Environment Degrades Performance





Different Readers Read at Different Speeds

Comparison of Read Speeds





Need Performance?

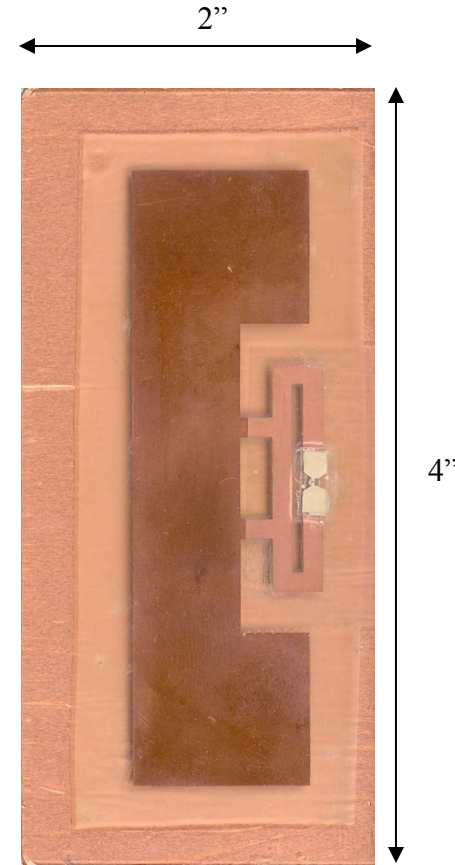
Lessons learned:

- ◆ Larger tags generally mean more performance
- ◆ Stay away from metal, water
- ◆ Use bi-static antennas / readers for long reads
- ◆ When all else fails, go active
- ◆ For sensing, you *need* active tags



Developments from KU

- ◆ 4 patents pending
- ◆ Manufacture agreement signed 3/23/07
- ◆ Rugged 2x4x.06" form factor
- ◆ UV / Abrasion coated
- ◆ Externally validated: 20' read distance on water, industrial environment





Future Technologies from KU

- ◆ High-performance “credit card” work-on-metal tag
- ◆ Work-on-metal, work-on-air low-cost foam spacer tag
- ◆ Rugged “stick” asset tag
- ◆ Low-cost sensing passive RFID tag



Future Technologies

◆ Tags:

- ◆ Increased read distance
- ◆ Increased reliability
- ◆ Lower cost

◆ Readers:

- ◆ Increased performance
- ◆ Smaller packages
- ◆ Lower cost

◆ Sensors:

- ◆ Increased capabilities
- ◆ Better / smaller / cheaper batteries



Conclusions

- ◆ For dock door use case: need UHF tags
- ◆ Passive tags:
 - ◆ Stay away from metal, water
 - ◆ Size matters (usually)
 - ◆ Use KU-tag (or other specialty tag) for hard-to-tag items
- ◆ Readers: Two antennas = better performance
- ◆ Sensing: active tags
 - ◆ +Orders-of-magnitude more margin
 - ◆ -Cost